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# The USB Bus

# usb: general ideas

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## **USB is a high speed serial bus**

- **Four wires:: D+, D-, 5V, GND**
  - ♦ **Differential signalling, NRZI, with bit stuffing**
  - ♦ **Current limit: 500mA**
  - ♦ **OTG connectors have a fifth pin: "ID"**
- **Packet-based communication**
- **Point-to-point physical connection**
  - ♦ **One of the parties is the controlling one**  
Called "usb host" or "usb master"
  - ♦ **The other party is only replying to queries**  
Called "usb device" or "usb slave"
- **You can use hubs to extend the bus**
  - ♦ **A hub device can be externally powered or not**
  - ♦ **Each bus can enumerate no more than 127 devices**
- **The specs include a special protocol for current management**

# USB-1, USB-2

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**USB-1 (v1.0: 1996, v1.1: 1998) supports the following speeds:**

- **Slow speed**
  - ♦ 1.5Mbit/s, max 1023 bytes per packet
- **Full speed**
  - ♦ 12Mbit/s, max 1023 bytes per packet

**Every millisecond, the host must send a SOF packet**

**USB-2 (v2.0: 2000) supports the following speeds:**

- **Slow speed**
- **Full speed**
- **High speed**
  - ♦ 480Mbit/s, 8kB per packet

**The host sends a SOF packet every 125 usecs (8kHz)**

**Beware: there are USB-2.0 devices that only support full-speed**

# USB3

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## **USB-3 (v3.0: 2010) adds "Super Speed" (5Gbit/s)**

- It uses additional data pairs to achieve higher speed
- 900mA current limit (was 500mA)
- Backward compatible with USB2 and USB1
- Not really relevant to the microcontroller world

## **USB-3.1 (2013), USB-3.2 (2017)**

- ....

# The USB hardware (ignoring v3 and later)

## **Lines should be equal length with 90 Ohm diff. impedance**

- Each wire should be terminated to a 45 Ohm transceiver

## **The 5V supply is just convenience**

- It is not related to signalling (which works at 3.3V or 0.8V)
- It is specified with 5% tolerance (4.75..5.25)
- Most chargers run a 5.3V or even a little more

## **Devices report presence with a 1.5k pull-up resistor (to 3.3V)**

- The host side pulls down with 15k.

## **Cable length is limited to 5 meters**

## **The chain is limited to 7 levels all-included (i.e. 5 hubs)**

# The USB protocol basics

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## **The protocol is completely master-driven**

- The slave must feature a good-enough clock
- "Internal RC" oscillators are not enough

## **Both master and slave devices are implemented in hardware**

- Software can't deal with speed and determinism of the bus

## **The master port is depicted as a "Root Hub"**

- A PC usually has several root hubs
- Root hubs can be single-port or multi-port

## **Bandwidth is effectively shared between devices**

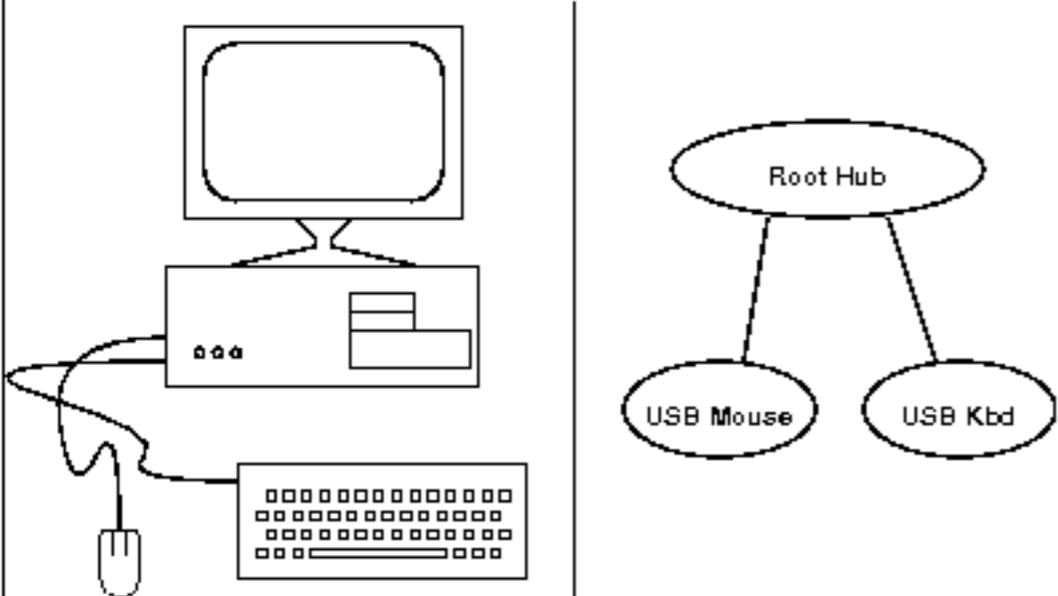
## **When a device appears, it must be enumerated**

- Hubs are enumerated too (including the root hub)

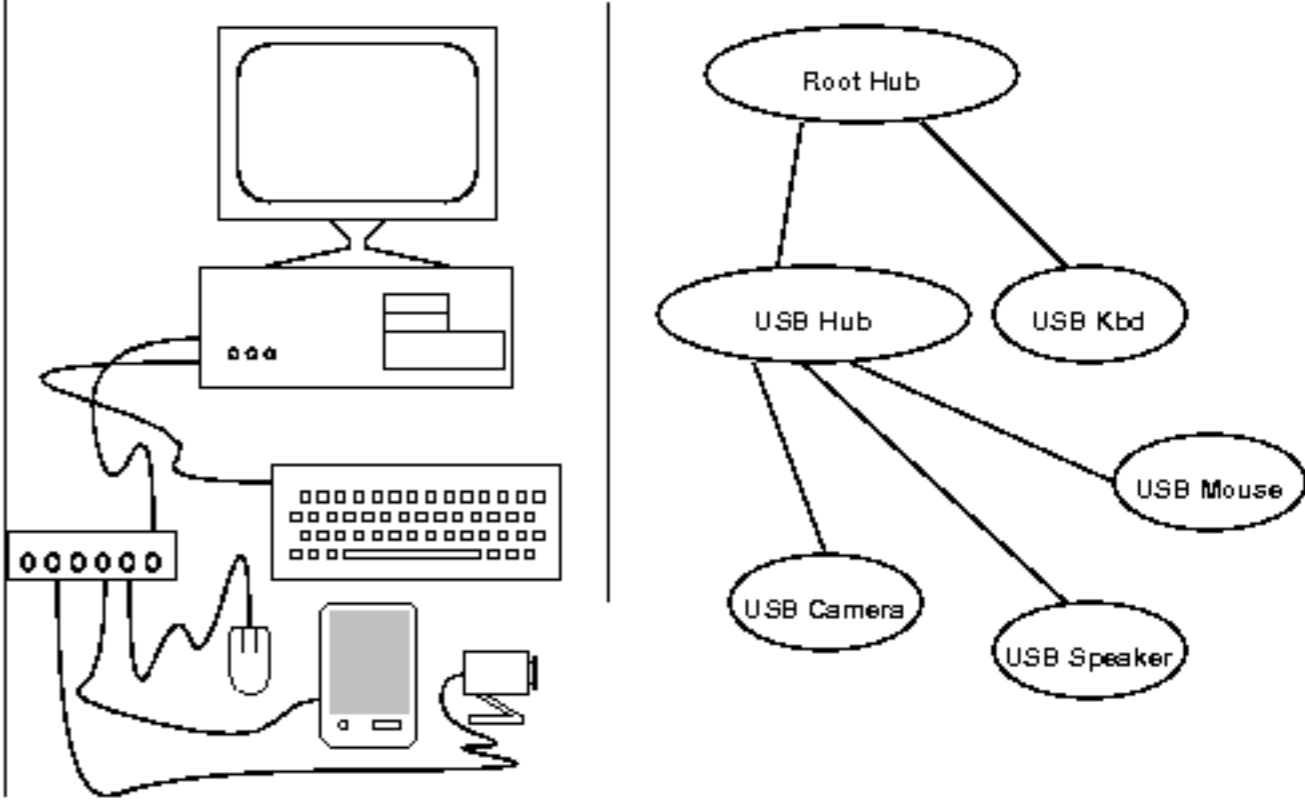
# Example of USB buses

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Simple USB layout



More Complex USB layout



# The USB protocol: endpoints and more

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## **Each device features a vendor and device ID, plus class**

- Vendor and device are 16 bits wide
  - ♦ This is artificial scarcity, designed by a greedy consortium
  - ♦ USB identifiers are very expensive, and must be renewed

## **Devices can feature more than one "Interface"**

- Packets are addressed to a specific interface
- Each interface is like a separate device

## **Each interface features several "endpoints"**

- Packets are addressed to a specific endpoint
- USB-1 was talking about "pipes", a now-forgotten word
  - ♦ Endpoints were the end points of each pipe
- An endpoint can be either input or output (as seen from the host)
- The standard defines 3 types of endpoints are defined (and "control")



# Endpoint types

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## Control

- EP0 always exists, and it is the **Control Endpoint**
  - ♦ It is **bidirectional**, with a **request/response protocol**

## Bulk

- **Data channels without timing constraints**
- **They are a one-way data stream**
- **Usually, you run them in pairs (input and output)**

## Interrupt

- **Input channel, much alike an interrupt event channel**
- **Actually, it's always the host who polls the device**

## Isochronous

- **Sustained data flow, with guaranteed bandwidth**
- **Typically used to deliver audio or video streams**

## **For all types, transmission is packet- and frame-oriented**

- **The receiver is aware of the size of each frame**
- **A packet can span multiple frames (e.g.: more than 64 bytes).**

# Enumeration

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## **When a device appears, it must be enumerated.**

- It initially responds to address 0
- The host queries device information
- It then assigns an address to the device
  - ◆ All of this happens on endpoint 0

## **With this new address, everything starts over**

- The host queries device information, again
- It collects identifiers and "strings"
- Eventually, the driver may take over and use the other endpoints

# Enumeration Example

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## Data collected with "usbmon" Linux, target is "hello.bin"

```
S Ci:000:00 s 80 06 0100 0000 0040 64 <
C Ci:000:00 0 64 = 12010001 00000040 c41060ea [...]
[...]
S Co:000:00 s 00 05 0024 0000 0000 0
C Co:000:00 0 0
S Ci:036:00 s 80 06 0100 0000 0012 18 <
C Ci:036:00 0 18 = 12010001 00000040 c41060ea 00010302 0101
[...]
S Ci:036:00 s 80 06 0300 0000 00ff 255 <
C Ci:036:00 0 4 = 04030904
S Ci:036:00 s 80 06 0302 0409 00ff 255 <
C Ci:036:00 0 12 = 0c036600 73006d00 6f007300
S Ci:036:00 s 80 06 0303 0409 00ff 255 <
C Ci:036:00 0 10 = 0a037200 75006200 6900
[...]
```

# Explanation of the above example

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## **USBMON is not a sniffer**

- It cannot look at the wire, only at higher levels
- USB frames and timing require specific hardware
- And USB is not a shared channel like Ethernet

## **"S" means "Submit" and "C" means "Complete"**

- The software stack is a state machine
- Every submit must be followed by a complete, possibly delayed

## **"Co" is "control out", we also have "Bo", "Ii" etc**

- "000:00" is endpoint 0 of device 0 (not enumerated yet)
- "036:00" is endpoint 0 of device 36 (after enumeration)

## **"64 <" at the end of a submit line is the input buffer size**

- The reply can be no bigger than that

# Writing a USB stack

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## **The USB protocol stack can be laid out in 2 or three levels**

- Hardware management (which may include low-level protocol)
- Optionally, common protocol procedures
- The actual device code (usb-serial, network, storage)

## **Then, higher levels (UDP/IP, FATFS, whatever) will be generic**

- The USB device driver will offer a non-usb API

## **Most USB implementations are state machines with callbacks**

- This can happen based on interrupts
- Or you can just poll the status bits